



An Orthogonal Polynomial Based Iterative Procedure for Finding the Root of the Equation $f(x) = 0$

E. J. Mamadu ^{a*}

^aDepartment of Mathematics, Delta State University, Abraka, Nigeria.

Author's contribution

The sole author designed, analysed, interpreted and prepared the manuscript.

Article Information

DOI: 10.9734/ARJOM/2023/v19i9708

Open Peer Review History:

This journal follows the Advanced Open Peer Review policy. Identity of the Reviewers, Editor(s) and additional Reviewers, peer review comments, different versions of the manuscript, comments of the editors, etc are available here: <https://www.sdiarticle5.com/review-history/102160>

Received: 11/05/2023

Accepted: 04/07/2023

Published: 20/07/2023

Original Research Article

Abstract

Iterative methods provide hope for many nonlinear engineering problems that cannot be solved through analytic procedures. In this article, orthogonal polynomial based iterative schemes are developed for the approximate solutions of nonlinear algebraic and transcendental equations. Basically, Mamadu-Njoseh orthogonal polynomials are employed as basis functions to derive the new iterative schemes called the "Mamadu Δ^2 and Δ^3 iterative schemes". Convergence analysis of the schemes shows the convergence rate as of order 3 and 4, respectively. Numerical experimental of the new schemes show the feasibility and correctness of the method.

Keywords: *Orthogonal polynomials; Mamadu-Njoseh polynomials; convergence; Newton-Raphson scheme; algebraic and transcendental equations.*

*Corresponding author: Email: emamadu@delsu.edu.ng;

1 Introduction

Nonlinear equations are frequently encountered in many engineering problems. An N coupled nonlinear equations in N variables, x_1, x_2, \dots, x_n , has the form [1,2]

$$\begin{aligned} G_1(x_1) &= 0 \\ G_2(x_2) &= 0 \\ &\vdots \\ G_N(x_n) &= 0, \end{aligned} \tag{1.1}$$

Equation(1.1) can be rewritten as

$$G(x) = \begin{pmatrix} G_1(x_1) \\ G_2(x_2) \\ G_3(x_3) \\ \vdots \\ G_N(x_n) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \tag{1.2}$$

More than one solution of x can exist that may satisfy (1.2). A typical example of (1.2) is the nonlinear characteristics equation of N th degree [3]. When $N = 1$ with the variable λ , we obtain N ordinary differential equations, which is relevant to the study of system analysis. Again, the simulation of chemical plants in its steady state can be modeled by thousands of coupled nonlinear equations involving several variables [4, 5].

A lot of constraints are encountered in solving (1.2) analytically, which may be due to perturbation, making of weak assumptions, linearization or quasi linearization, and among others. Consequently, iterative schemes have been adopted by various mathematicians as means of solving these equations. Some popular iterative techniques over the years include, the bisection method, Newton-Raphson method, fixed point iteration method, successive substitution method, Muller’s method, Secant method, and among others. Amongst others, the Newton-Raphson is quite easy to implement and converges fast but requires more computational stress [6–9].

This paper offers to derive and implement new iterative scheme that performs better than other methods, especially the Newton-Raphson method. The new scheme is orthogonal polynomials based, that is, applying Mamadu-Njoseh polynomials [10-17] as basis functions as series solutions subjects to three relevant conditions. The class of algebraic and transcendental equations and possibly any nonlinear equations are employed to test the rate of convergence, accuracy and effectiveness of the new scheme. For future references, the new iterative schemes shall be called “Mamadu Δ^2 and Δ^3 iterative methods”.

2 Derivation of Mamadu Δ^2 And Δ^3 Iterative Schemes

In this section, we shall derive new iterative formulas for the approximate solutions of both algebraic and transcendental equations that depend on the degree of orthogonal polynomials. Basically, we derive here the iterative formulas with orthogonal polynomials of degrees two and three, respectively.

Now, let $g(x)$ define an orthogonal polynomial of the form

$$g(x) = \sum_{i=0}^n a_i \varphi_i(x), a_0 \neq 0, \tag{2.1}$$

where a_i ’s are constants and $\varphi_i(x), i = 0,1,2, \dots, n$, are Mamadu-Njoseh polynomials defined in $[-1, 1]$ with respect to the weight function $w(x) = 1 + x^2$. For $n = 2$ in (2.1), we obtain a second degree polynomial of the form

$$g(x) = a_0 + a_1x + \frac{a_2}{3}(5x^2 - 2) = 0 \tag{2.2}$$

To estimate a_0, a_1, a_2 in (2.2), we will prescribe three conditions on $g(x)$ as

$$g_k = a_0 + a_1 x_k + \frac{a_2}{3} (5x_k^2 - 2) \tag{2.3}$$

$$g'_k = a_1 + \frac{10x_k a_2}{3} \tag{2.4}$$

$$g''_k = \frac{10a_2}{3} \tag{2.5}$$

Solving (2.3) – (2.5) we obtain,

$$\left. \begin{aligned} a_0 &= \frac{1}{2} g''_k x_k^2 - g'_k x_k + g_k + \frac{1}{5} g''_k \\ a_1 &= g''_k x_k + g'_k \\ a_2 &= \frac{3}{10} g''_k \end{aligned} \right\} \tag{2.6}$$

Substituting (2.6) into (2.2) to obtain

$$\frac{1}{2} g''_k x_k^2 - g'_k x_k + g_k - x g''_k x_k + \frac{1}{2} g''_k x^2 + x g'_k = 0 \tag{2.7}$$

Simplifying (2.7) further, we have,

$$(-x_k + x) g'_k + \frac{1}{2} g''_k x_k^2 + g_k - x g''_k x_k + \frac{1}{2} g''_k x^2 = 0,$$

which implies,

$$x_{k+1} - x_k = -\frac{1}{g'_k} \left(\frac{1}{2} g''_k x_k^2 + g_k - x_{k+1} g''_k x_k + \frac{1}{2} g''_k x_{k+1}^2 \right) \tag{2.8}$$

By Newton method

$$x_{k+1} = x_k - \frac{g_k}{g'_k} \tag{2.9}$$

Using (2.9) on (2.8), we obtain,

$$x_{k+1} = x_k - \frac{g_k (g_k g''_k + 2g_k'^2)}{g_k^3}, \tag{2.10}$$

which is the Mamadu Δ^2 iterative scheme.

Let $g(\beta) = 0$. According to Mamadu's Δ^2 iterative scheme, we write $x_k = x_{k-1} - \frac{g_{k-1} (g_{k-1} g''_{k-1} + 2g_{k-1}'^2)}{g_{k-1}^3}$. If $g'(\beta) = g''(\beta) = g'''(\beta) \neq 0$, then by Taylor's theorem for some $x_k \leq \sigma \leq \beta$, we have,

$$\begin{aligned} 0 &= g(\beta) \\ &= g(x_k) + (\beta - x_k) g'(x_k) + \frac{(\beta - x_k)^2}{2!} g''(x_k) + \frac{(\beta - x_k)^3}{3!} g'''(x_k) \end{aligned} \tag{2.11}$$

$$-g(x_k) = (\beta - x_k) g'(\sigma) + \frac{(\beta - x_k)^2}{2!} g''(\sigma) + \frac{(\beta - x_k)^3}{3!} g'''(\sigma) \tag{2.12}$$

By error definition, we have,

$$e_{k+1} = |\beta - x_{k+1}|$$

$$\begin{aligned}
 &= \left| \beta - \left(x_k - \frac{g_k(g_k g_k'' + 2g_k'{}^2)}{g_k'{}^3} \right) \right| \\
 &= \left| \beta - \left(x_k + \frac{\left((\beta-x_k)g'(\sigma) + \frac{(\beta-x_k)^2}{2!}g''(\sigma) + \frac{(\beta-x_k)^3}{3!}g'''(\sigma) \right) \left(- \left((\beta-x_k)g'(\sigma) + \frac{(\beta-x_k)^2}{2!}g''(\sigma) + \frac{(\beta-x_k)^3}{3!}g'''(\sigma) \right) g''(x_k) + 2g'(x_k)^2 \right)}{g'(x_k)^3} \right) \right| \tag{2.13}
 \end{aligned}$$

Further simplification and analysis of (2.13) yields

$$\begin{aligned}
 &= \left| -\frac{1}{36} \frac{g'(\sigma)g'''(\sigma)^2}{g'(x_k)^3} (\beta - x_k)^3 \right| \\
 &= \left| \frac{1}{36} \frac{g'(\sigma)g'''(\sigma)^2}{g'(x_k)^3} \right| |\beta - x_k|^3 \\
 &= \left| \frac{1}{36} \frac{g'(\sigma)g'''(\sigma)^2}{g'(x_k)^3} \right| e_n^3
 \end{aligned}$$

In other words, we have

$$\frac{e_{n+1}}{e_n^3} = \left| \frac{1}{36} \frac{g'(\sigma)g'''(\sigma)^2}{g'(x_k)^3} \right|$$

Thus,

$$\lim_{n \rightarrow \infty} \left(\frac{e_{n+1}}{e_n^3} \right) = \left| \frac{1}{36} \frac{g'(\sigma)g'''(\sigma)^2}{g'(x_k)^3} \right| = k \neq 0.$$

Hence, the order of convergence of Mamadu’s Δ^2 scheme is cubic and the error term (which is asymptotic) is $\left| \frac{1}{36} \frac{g'(\sigma)g'''(\sigma)^2}{g'(x_k)^3} \right| \neq 0$, and $g'(\beta) = g''(\beta) = g'''(\beta) \neq 0$.

Similarly, for $n = 3$ in (2.1) and repeating the above process, we obtain the Mamadu Δ^3 iterative scheme iterative formula as:

$$x_{k+1} = x_k + \frac{g_k(g_k^2 g_k''' - 3g_k g_k' g_k'' - 6g_k'{}^3)}{6g_k'{}^4} \tag{2.14}$$

By using same approach of analysis as above, the rate of convergence of (2.14) is of order 4.

3 Convergence Analysis

We consider the following theorems.

Theorem 3.1. Suppose $g(x) \in [a, b] \forall x \in [a, b]$ defines a differentiable function with the condition $\max|g(x)| = A < 1$, then $x_{k+1} = g(x_k)$ for $k = 0, 1, 2, \dots$ and $x_0 \in [a, b]$ converges to the required root $\beta \in [a, b]$.

Proof. Let $\beta = \lim_{k \rightarrow \infty} x_k$ be given. Then, $\beta = \lim_{k+1 \rightarrow \infty} x_k = \lim_{k \rightarrow \infty} g(x_k) = g(\lim_{k \rightarrow \infty} x_k) = g(\beta)$. Also, for $\min\{\beta, x_k\} \leq r \leq \max\{\beta, x_k\}$, we have $|\beta - x_{k+1}| = |g(\beta) - g(x_k)| \leq |g'(r)| |\beta - x_k| \leq A |\beta - x_k|$. Repeating the process, we obtain $|\beta - x_{k+1}| \leq A^{k+1} |\beta - x_0|$. Since $A < 1$, we have that $\lim_{k+1 \rightarrow \infty} A^{k+1} = 0 \Rightarrow \lim_{k+1 \rightarrow \infty} \beta - x_{k+1} = 0 \Rightarrow \lim_{k \rightarrow \infty} x_k = \beta$.

Theorem 3.2. If $g'''(x)$ exist and $x = \beta$ is a root of $g(x) = 0$, then \exists a $\delta > 0$ such that $\{x_k\}_0^\infty$ defined by (2.11) converges to β for any $x_0 \in [\beta - \delta, \beta + \delta]$.

Proof. Obviously $g(\beta) = 0$ and $g''(\beta) = g'''(\beta) \neq 0$. Since $g'(x)$, $g''(x)$ and $g'''(x)$ are continuous and $g'(x) = g''(x) = g'''(x) \neq 0$, $\exists \alpha > 0$ such that $g'(x) = g''(x) = g'''(x) \neq 0 \forall x \in [\beta - \alpha, \beta + \alpha]$. Also, since $g'(\beta) = g''(\beta) = g'''(\beta) = 0$ and $g'(x), g''(x)$ and $g'''(x)$ are continuous, $\exists 0 < \delta \leq \alpha$ such that $|g'(x)| < 1, |g''(x)| < 1$ and $|g'''(x)| < 1$ for $[\beta - \delta, \beta + \delta]$. Hence, by theorem 3.1, (2.10) and (2.14) converges to β .

4 Numerical Perspectives and Discussion

In this section, we experiment the iterative schemes (2.10) and (2.14) on some algebraic and transcendental equations to show the accuracy, effectiveness and rate of convergence as compared with the Newton-Raphson method.

Example 4.1. Compute the approximate root of $e^x \sin(x) - x^2 = 0$, correct to three decimal places with initial approximation $x_0 = 3$.

Example 4.2. Obtain the root of the $x \log(x) = 1.2$, correct to three decimal places with initial approximation $x_0 = 2$.

Example 4.3: Compute the positive root of the equation $x^2 - 5x + 2 = 0$, correct to four decimal places with $x_0 = 0.5$.

Results for the above examples are presented in the tables below.

Table 1. Computed results for example 4.1

k	Mamadu Δ^2 method	Mamadu Δ^3 method	Newton-Raphson method
0	2.667897090	2.673977394	2.732513710
1	2.618277339	2.618462144	2.631993135
2	2.618039570	2.618039570	2.618254091
3	2.618039570	2.618039570	2.618014029
4	-	-	2.618013958
5	-	-	2.618039570

From Table 1, it requires three iterations for Mamadu Δ^2 and Δ^3 iterative schemes to achieve absolute convergence. Whereas, Newton-Raphson iterative scheme requires six iterations to obtain the required roots. Hence, the computed root is 2.618 correct to 3 decimal places.

Table 2. Computed results for example 4.2

k	Mamadu Δ^2 method	Mamadu Δ^3 method	Newton-Raphson method
0	2.715530523	2.728762614	2.813164836
1	2.740645649	2.740646068	2.741109567
2	2.740646096	2.740646096	2.740646116
3	2.740646096	2.740646096	2.740646097
4	-	-	2.740646096

It was observed that the Newton-Raphson method required five iterations to arrive at the root, whereas Mamadu Δ^2 and Δ^3 iterative methods arrived at the root in three iterations. The computed root of the equation is 2.741 correct to three decimal places.

Table 3. Computed results for example 4.3

k	Mamadu Δ^2 method	Mamadu Δ^3 method	Newton-Raphson method
0	0.43847656250	0.43847656250	0.4375000000
1	0.43834471871	0.43834471871	0.4384469697
2	0.43834471871	0.43834471871	0.4384471873
3	-	-	0.4384471871

Here, the Mamadu Δ^2 and Δ^3 iterative methods required only two iterations to obtain the required root, whereas the Newton-Raphson scheme required four iterations to arrive at the computed root. Thus, the computed root for the equation is 0.4384 correct to 4 decimal places.

5 Conclusion

In this article, we have considered orthogonal based iterative schemes for seeking the approximate roots of algebraic and transcendental equations. The new derived iterative schemes named “Mamadu Δ^2 and Δ^3 iterative schemes” perform incredibly well requiring just few iterations to obtain the required roots as shown in the Tables 1 – 3. The Mamadu Δ^2 and Δ^3 iterative schemes in comparison with the Newton-Raphson method converge faster and better. Thus, it is recommended that these new iterative schemes be incorporated as new iterative methods for finding the roots of nonlinear equations.

Competing Interests

Author has declared that no competing interests exist.

References

- [1] Brown KM. In Numerical Solution of Systems of Nonlinear Algebraic Equations, G.D. Bryrne and C.A Hall, eds., Academic, New York; 1973.
- [2] Forsythe GE, Moler CB. Computer solution of linear algebraic systems, Prentice Hall, Englewood Cliffs, N.J; 1967.
- [3] Burden RL, Faires JD. Numerical analysis, 3rd ed., Prindle, Weber and Schmidt, Boston, M.A; 1985.
- [4] Smith JM, Van Ness HC, Abbott M. Introduction to chemical engineering thermodynamics, 7th ed. McGraw-Hill, New York; 2004.
- [5] Lapidus L. Digital Computation for Chemical Engineering, McGraw Hill, New York; 1962.
- [6] Comte SD, de Boor C. Elementary Numerical analysis, 2nd ed., McGraw Hill. New York; 1972.
- [7] Householder AS. Principles of numerical analysis, McGraw Hill, New York. 1953;134.
- [8] Goldstine HH. A history of numerical analysis from the 16th, thru the 19th century, Springer Verlag, New York; 1977.
- [9] Powell MJD. In numerical methods for nonlinear algebraic equations, P. RRabinowitz, ed., Gordon and Breach, New York; 1970.
- [10] Mamadu EJ, Njoseh IN, Ojarikre HI, Space discretization of time-fractional telegraph equation with Mamadu-Njoseh basis functions. Appl Math. 2022;13(9):760-73.
- [11] Mamadu EJ, Ojarikre HI, Njoseh IN. Convergence analysis of space discretization of time-telegraph equation. Math Stat. 2023;11(2):245-51.

- [12] Mamadu EJ, Ojarikre HI, Njoseh IN. An error analysis of implicit finite difference method with mamadu-njoseh basis functions for time fractional telegraph equation. Asian Res. J. Math. 2023;19(7): 20- 30. Article no.ARJOM.98744.
- [13] Mamadu EJ, Ojarikre HI. Reconstructed elzaki transform method for delay differential equations with mamadu-njoseh polynomials. Journals of Mathematics and System Science. 2019;9:41-45.
- [14] Tsetimi J, Mamadu EJ. Perturbation by decomposition: A new approach to singular initial value problems with Mamadu-Njoseh basis functions, Journal of Mathematics and System Science; 2020. Available:<http://dx.doi.org/10.17265/2159-5291/2020.01.003>
- [15] Mamadu EJ, Njoseh IN. Certain orthogonal polynomials in orthogonal collocation methods of solving integro-differential equations (fides). Transactions of the Nigeria Association of Mathematical Physics. 2016;2:59-64.
- [16] Ogeh KO, Njoseh IN. Modified variational iteration method for solving boundary value problems using Mamadu-Njoseh polynomials. International Journal of Engineering and future technology. 2019;16(4):24 – 36.
- [17] Mamadu EJ. Numerical approach to the black-scholes model using Mamadu-Njoseh polynomials as basis functions. Nigerian Journal of Science and Environment. 2020;18(2):108-113.

© 2023 Mamadu; This is an Open Access article distributed under the terms of the Creative Commons Attribution License (<http://creativecommons.org/licenses/by/4.0>), which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

Peer-review history:

The peer review history for this paper can be accessed here (Please copy paste the total link in your browser address bar)

<https://www.sdiarticle5.com/review-history/102160>